

1. **Nonlinear Equations** Given scalar equation  $f(x) = 0$

- a. describe the convergence of the root-finding algorithm.
- a sufficient condition for convergence is established a priori
- the root-finding algorithm converges or not.
- d. describe the algorithm as a fixed point iteration. • a sufficient condition for a general fixed point iteration to converge.
- e. apply the iteration or fixed point iteration of the root-finding algorithm and develop an alternative root-finding algorithm.

**Solution**

a. Newton's method Given  $x_0$  let

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}, \quad n = 0.$$

• the algorithm Given  $x_0, x_1$  let

$$x_{n+1} = x_n - f(x_n) \frac{x_n - x_{n-1}}{f(x_n) - f(x_{n-1})} \quad n = 1.$$

Newton's method of  $f(x) = 0$ . Suppose there is an interval  $E = [a, b]$  such that  $f(a) \cdot f(b) < 0$  and  $f'(x)$  are continuous on  $E$  and

$$\max_{x \in E} \frac{|f'(x)|}{|f(x)|} = M,$$

and  $M < 1.0$ . Then for any  $x_0 \in E$  Newton's method will converge in rate 2.0.

• the algorithm under the sufficient conditions if  $x_0$  and  $x_1$  are in  $E$  the algorithm will converge in rate  $\frac{1+\sqrt{5}}{2} \approx 1.62$ .

• see inson pages 5, 60.

d. define

$$g(x) = x - \frac{f(x)}{f'(x)}.$$

Ne on s<sup>1</sup> e od an e as as Given  $x$

## Numerical quadrature:

2. Assume that a quadrature rule, when discretizing with  $n$  nodes, possesses an error expansion of the form

$$I - I_n = \frac{c_1}{n} + \frac{c_2}{n^2} + \frac{c_3}{n^3} + \dots$$

Assume also that we, for a certain value of  $n$ , have numerically evaluated  $I_n$ ,  $I_{2n}$  and  $I_{3n}$ .

- Derive the best approximation that you can for the true value  $I$  of the integral.
- The error in this approximation will be of the form  $O(n^{-p})$  for a certain value of  $p$ . What is this value for  $p$ ?

## **Solution:**

- With three numerically evaluated values, we can solve for three variables. For these we want to choose  $I$ ,  $c_1$  and  $c_2$ , at which point we only care about the obtained value for  $I$ . Abbreviating  $\frac{c_1}{n} = d_1$  and  $\frac{c_2}{n^2} = d_2$ , we thus obtain the relations

$$\begin{aligned} I - I_n &= d_1 + d_2 \\ I - I_{2n} &= \frac{1}{2}d_1 + \frac{1}{4}d_2 \\ I - I_{3n} &= \frac{1}{3}d_1 + \frac{1}{9}d_2 \end{aligned} ,$$

or, written in the usual linear system form (separating 'knowns' from 'unknowns')

$$\begin{bmatrix} 1 & -1 & -1 \\ 1 & -\frac{1}{2} & -\frac{1}{4} \\ 1 & -\frac{1}{3} & -\frac{1}{9} \end{bmatrix} \begin{bmatrix} I \\ d_1 \\ d_2 \end{bmatrix} = \begin{bmatrix} I_n \\ I_{2n} \\ I_{3n} \end{bmatrix}$$

from which follows

$$I = \frac{1}{2}(I_n - 8I_{2n} + 9I_{3n}).$$

- With the first two terms in the error expansion eliminated, it will continue from the third term and onwards (with modified coefficients), i.e. the error in the approximation above will be of the form  $O(n^{-3})$ .



#### 4. Linear Algebra

Consider the  $n \times n$  nonsingular matrix  $A$ . The Frobenius norm of  $A$  is given by

$$\|A\|_F = \sqrt{\sum_{i,j} a_{ij}^2}$$

Consider the error matrix  $E$  in all Frobenius norms. The error matrix  $E$  is given by  $E = A - \hat{A}$  is the Frobenius norm of  $E$  is given by  $\|E\|_F = \sqrt{\sum_{i,j} e_{ij}^2}$ .

clearly

$$A - A U \Sigma^{-1} V$$

is singular.

Let  $u_1, u_2, \dots, u_n$  and  $v_1, v_2, \dots, v_n$  be a basis for  $U$  and  $V$  respectively. Then  $U = \sum_{j=1}^n u_j u_j^T$  and  $V = \sum_{j=1}^n v_j v_j^T$ . Then

$$A - A U \Sigma^{-1} V = A - \sum_{j=1}^n u_j u_j^T A \Sigma^{-1} v_j v_j^T$$

and the Frobenius norm is

$$\|A - A U \Sigma^{-1} V\|_F^2 = \sum_{j=1}^n \|u_j u_j^T A \Sigma^{-1} v_j v_j^T\|_F^2 = \sum_{j=1}^n \sigma_j^2$$

or

$$\|A - A U \Sigma^{-1} V\|_F = \sqrt{\sum_{j=1}^n \sigma_j^2}$$

Since  $A$  is any matrix,  $A - A U \Sigma^{-1} V$  is singular. Hence there is a vector  $w$  such that

$$A w = 0.$$

No

$$\min_{\|z\|=1} \|A z\| = \min_{\|w\|=1} \|A w\| = \sigma_n$$

is the smallest singular value of  $A$ . Since  $A$  is real and symmetric, the Frobenius norm of  $A$  is

$$\|A\|_F = \sqrt{\sum_{i=1}^n \sigma_i^2}$$

is

$$\|A\|_F = \sqrt{\sum_{i=1}^n \sigma_i^2}$$

Therefore, the singular values of  $A$  are the square roots of the eigenvalues of  $A^T A$ . If  $\lambda$  is an eigenvalue of  $A^T A$ , then  $\sqrt{\lambda}$  is a singular value of  $A$ . Conversely, if  $\sigma$  is a singular value of  $A$ , then  $\sigma^2$  is an eigenvalue of  $A^T A$ . Hence, the Frobenius norm of  $A$  is the square root of the sum of the squares of the singular values of  $A$ .

## Numerical ODE:

5. Consider using forward Euler (same as AB1; Adams-Bashforth of first order) as a predictor, and the trapezoidal rule (same as AM2; Adams Moulton of second order) as a corrector for solving the ODE  $y' = f(t, y)$ .
  - a. Write down the explicit steps that need to be taken in order to advance the numerical solution from time  $t_n$  to time  $t_{n+1} = t_n + k$ .
  - b. Determine the order of the combined scheme. In case you know a theorem that gives the order directly, you may quote this *in its general form*, i.e. do not just state the answer in the present special case.
  - c. The figure to the right illustrates the stability domain of the scheme. Prove that  $(-2, 0)$  is the leftmost point

## 6. Partial Differential Equations

Consider the steady state advection-diffusion equation in one space dimension

$$- \kappa u_{xx} + bu = f, \quad x \in (0, 1)$$

with boundary conditions  $u(0) = u(1) = 0$  and the assumption that  $\kappa > 0$  and  $b > 0$  or  $x \in (0, 1)$

and the right-hand side  $f$  is either a constant or a function. In the case of a constant  $f$ , the solution is a linear function. In the case of a function  $f$ , the solution is a function. The linear system  $Ax = b$  and  $A$  is a tridiagonal matrix.

Assume  $\kappa > 0$  and  $b > 0$  are constants. The relationship between  $\kappa$  and  $b$  is assumed to be linear. The eigenvalues of  $A$  are real and ordered  $\lambda_1 < \lambda_2 < \dots < \lambda_n$ .

For constants  $\kappa > 0$  and  $b > 0$ , the Gershgorin circles of the eigenvalues of  $A$  are **upwind** directed.

Now consider the parabolic equation assuming  $\kappa > 0$  and  $b > 0$  are constants

$$u_t - \kappa u_{xx} + bu = f, \quad x \in (0, 1)$$

where  $f$  is the **Forward** derivative or the advection term.

Reference: [1] G. I. Bell, *Journal of Computational Physics*, 1984, 53, 1-16. doi:10.1016/0021-9991(84)90001-0



ere  $i = X_{-1}, X_{+1}$ .

e en ered i eren es en il $_{\xi}$  or e se ond  $\xi$  is

$$b_X \frac{-u_{X-1} - u_{X+1}}{2h} = b_X u_{X_{\xi}} - \frac{h^2}{12} b_X u^{(3)},$$

ere  $i = X_{-1}, X_{+1}$ .

e ind i eren es en il $_{\xi}$  or e se ond  $\xi$  is  $\xi$  or  $b_X > 0$

$$b_X \frac{-u_{X-1} - u_X}{h} = b_X u_X - \frac{h}{2} b_X u,$$

ere  $i = X_{-1}, X$  and  $\xi$  or  $b_X < 0$

$$b_X \frac{-u_X - u_{X+1}}{h} = b_X u_{X_{\xi}} - \frac{h}{2} b_X u,$$

ere  $i = X, X_{+1}$ .

i en ered di eren es e linear sys  $\mathcal{A}$  is ridia onal deno ed y

$$\mathcal{A} = \frac{1}{h^2} \text{tri} \left[ -a_X - h/2, \frac{1}{2} b_X \quad a_X - h/2, a_{X_{\xi}} - h/2 \quad -a_{X_{\xi}} - h/2, -\frac{h}{2} b_X \right]$$

For  $\rightarrow$  indifference and  $\rightarrow$  on  $\mathbb{R}^n$  if  $a >$